

# *Deep Learning*



분리각(이론/실제) 목적구/수구 회전

*Yoonjoong Kim*

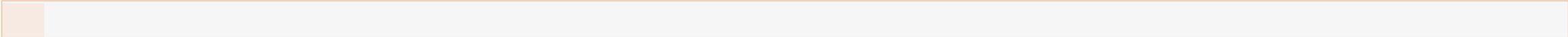
*Department of Computer Engineering, Hanbat National University*

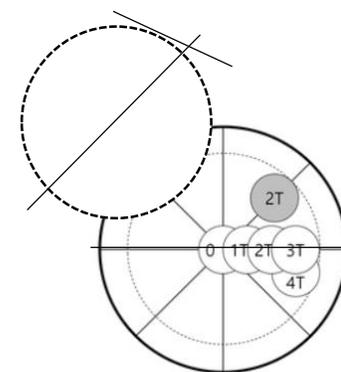
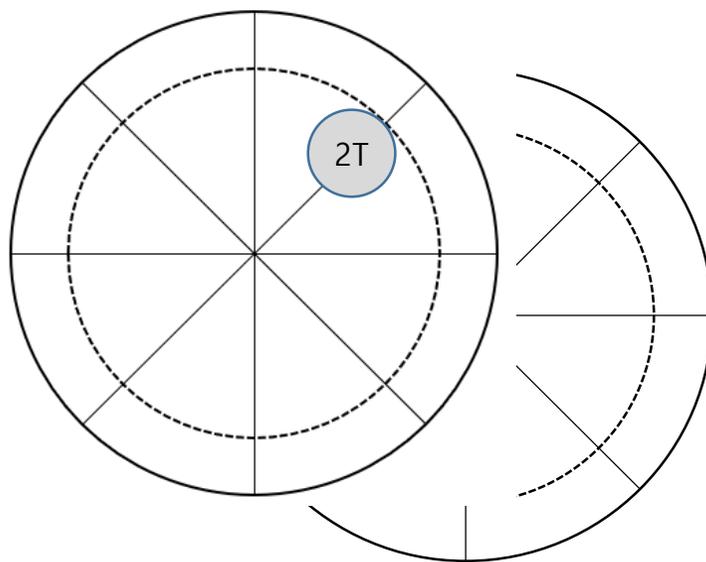
*yjkim@hanbat.ac.kr*

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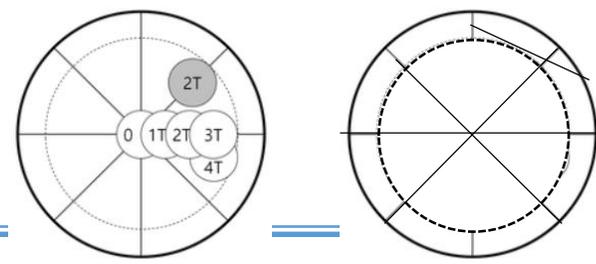
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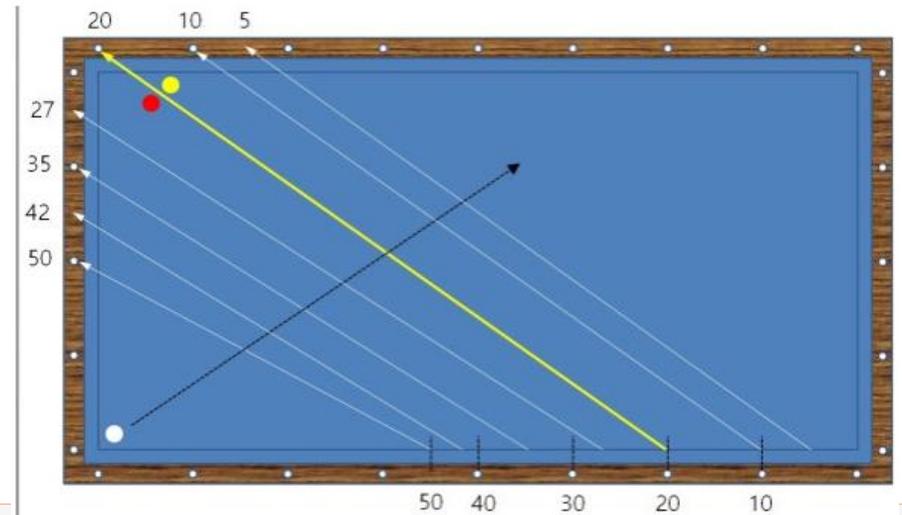
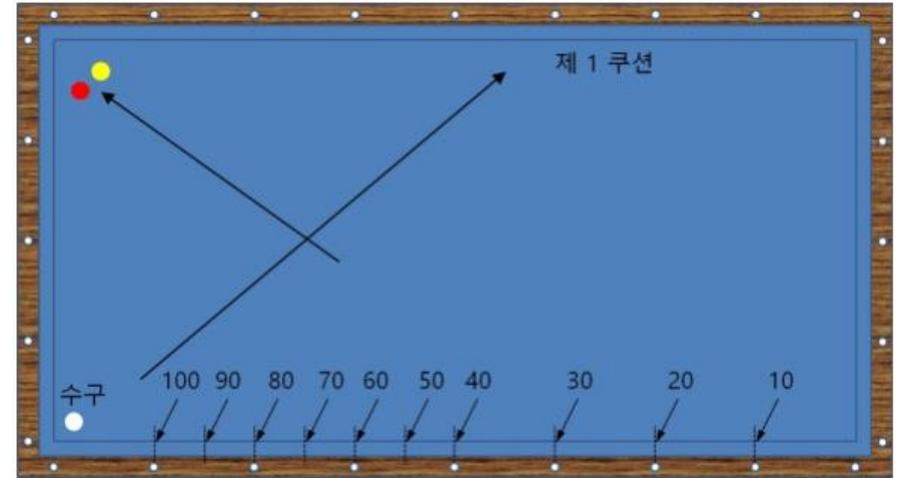
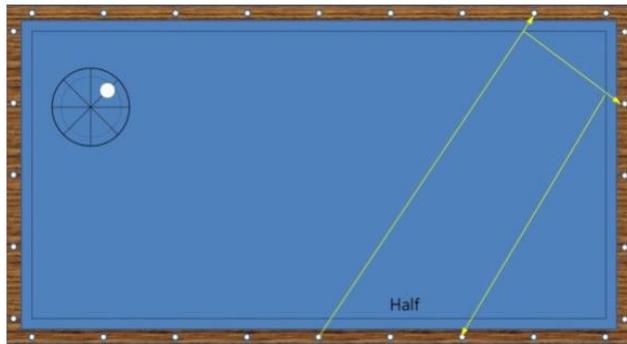
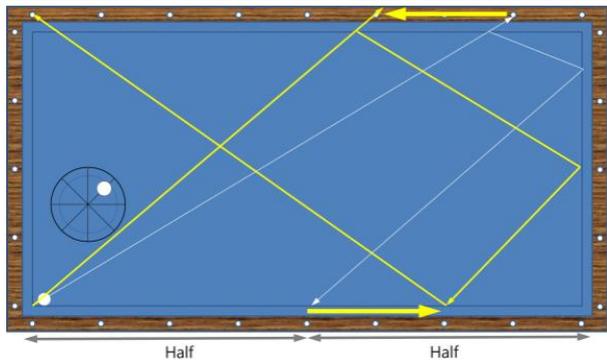
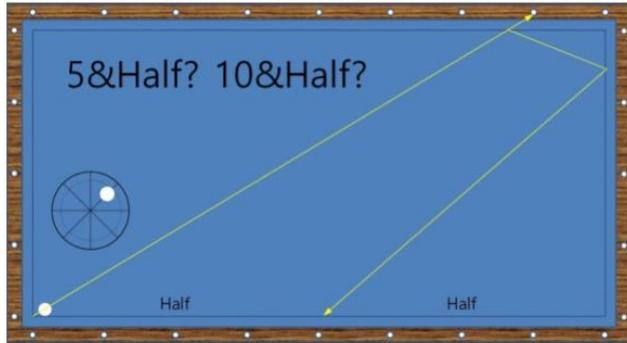
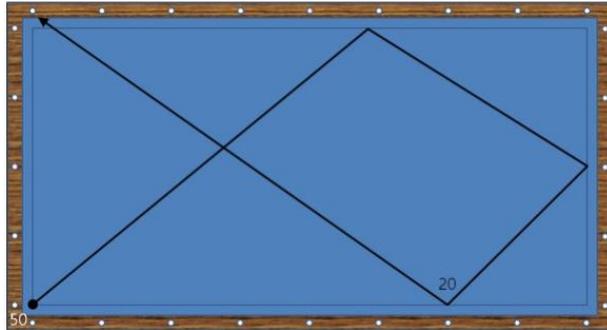
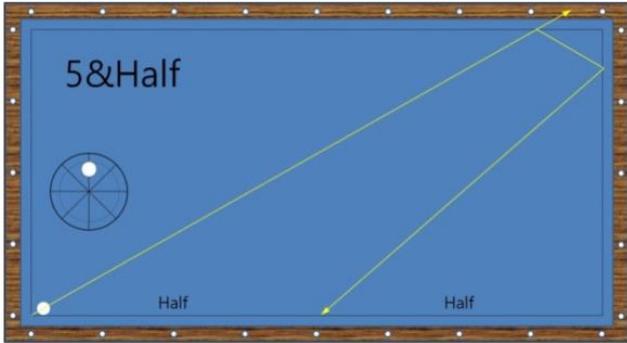


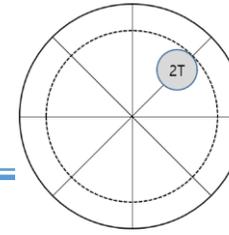


# 5&half system

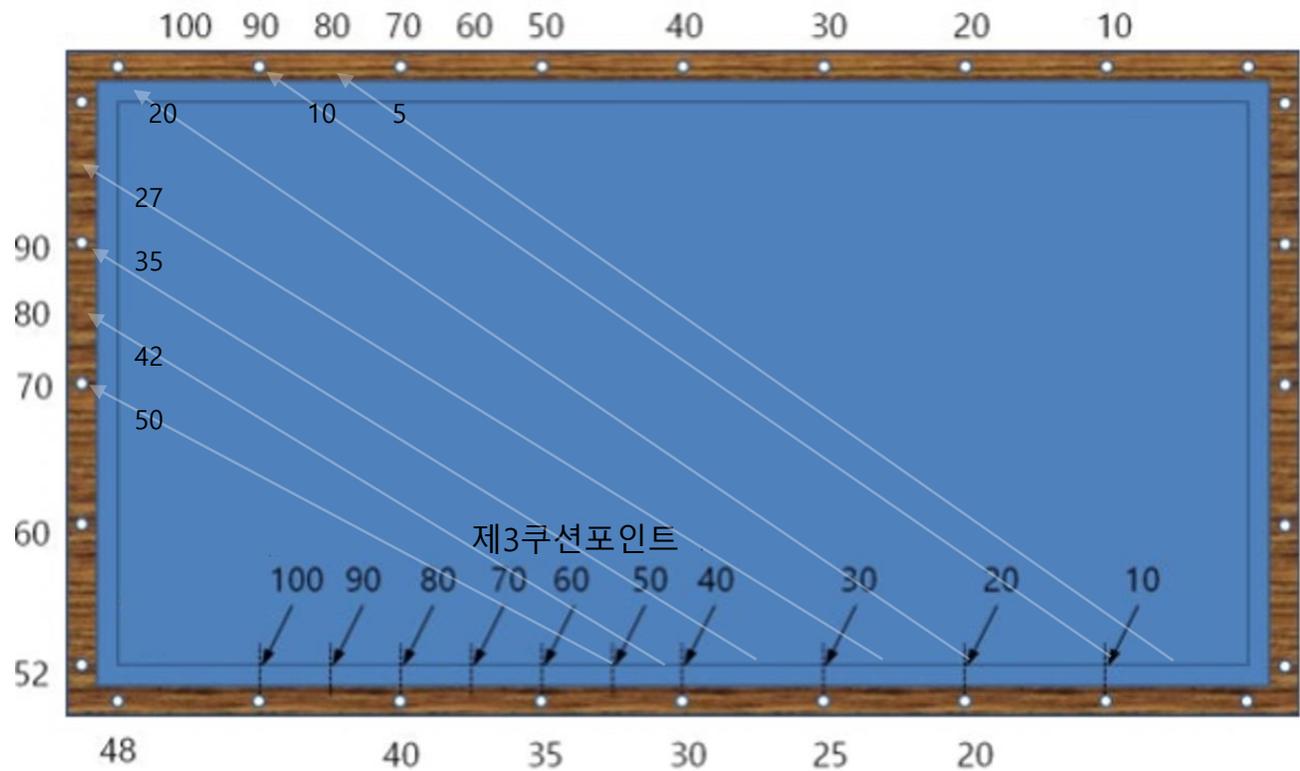


5&half system의 기본형

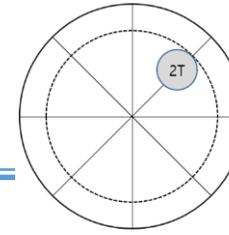




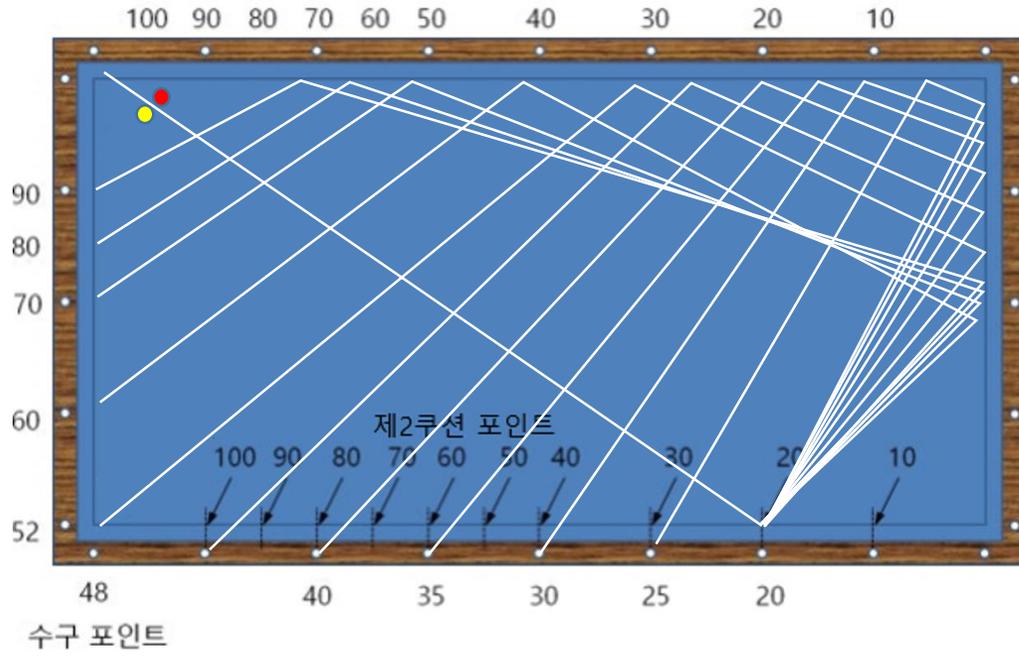
제1쿠션포인트



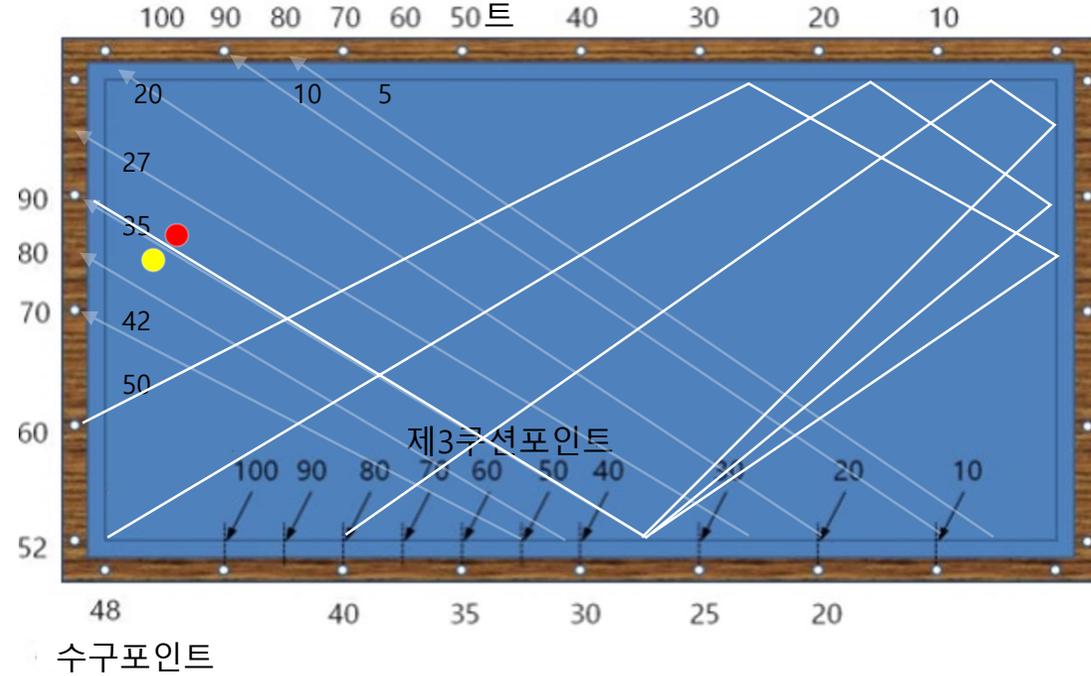
수구포인트

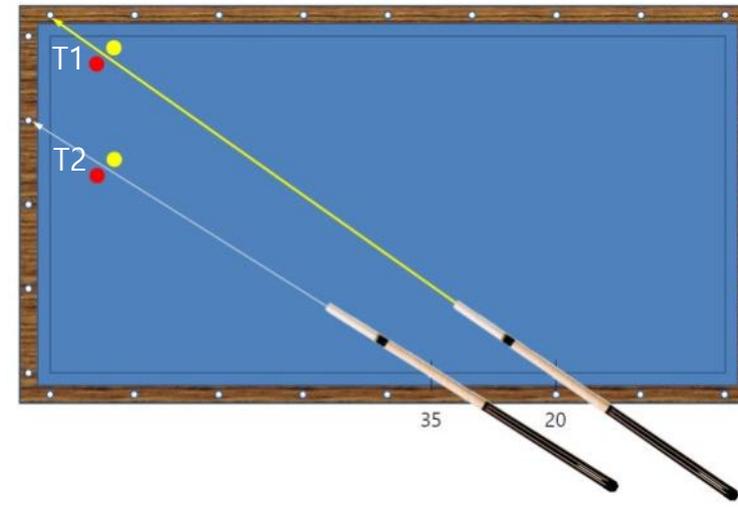
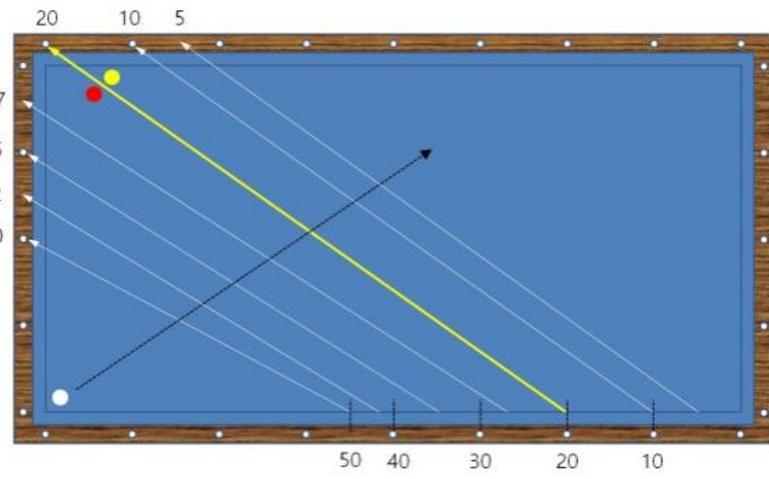
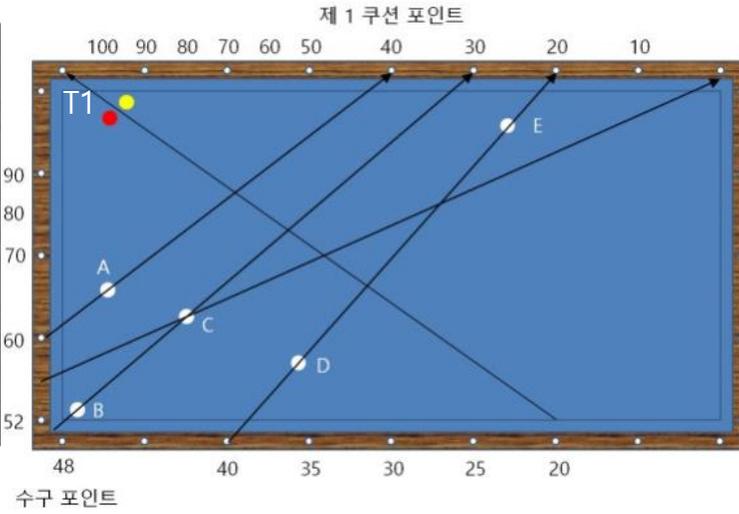
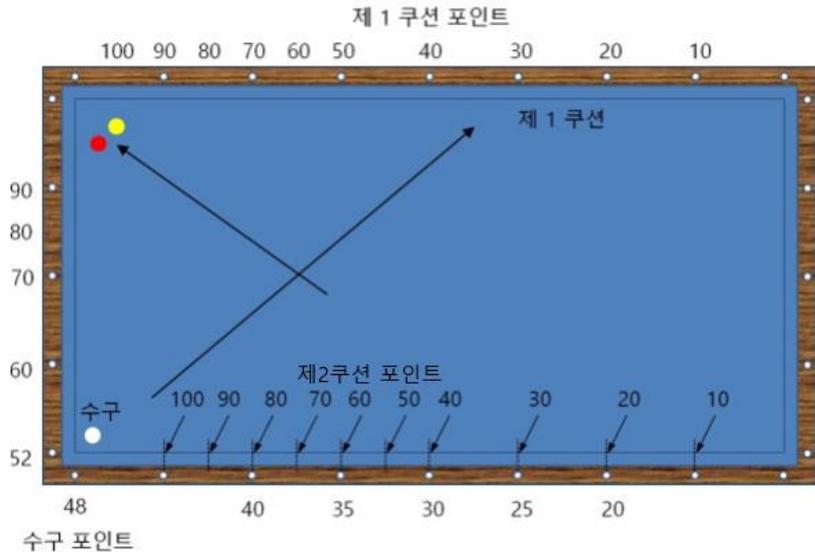
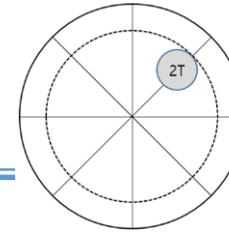


제 1 쿠션 포인트



제 1 쿠션 포인트





수구포인트=1쿠션포인트+2쿠션포인트

4쿠션포인트:제2목적구  
3쿠션포인트 계산  
1쿠션포인트 = 수구포인트-3쿠션포인트

C 수구포인트 : 50  
T1 제2목적구의 연장선=> 3쿠션포인트 계산  
3쿠션포인트 : 20  
1쿠션포인트 = 50-20=30

A 수구포인트 : 60  
T1 제2목적구의 연장선=> 3쿠션포인트 계산  
3쿠션포인트 : 20  
1쿠션포인트 = 60-20=40

D 수구포인트 : 40  
T1 제2목적구의 연장선=> 3쿠션포인트 계산  
3쿠션포인트 : 20  
1쿠션포인트 = 60-20=40

C 수구포인트 : 50  
T2 제2목적구의 연장선=> 3쿠션포인트 계산  
3쿠션포인트 : 35  
1쿠션포인트 = 50-35=15